



# iccMAX in Barbieri

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# Outline

1. Barbieri
2. What is texture?
3. Texture models
4. Roughness correction in iccMAX

# 1. Barbieri



Provincia di Bolzano,  
Italy



15 employees  
Service center in America,  
Europe and Asia



R&D, Assembling  
Quality control



Advanced patented technology

# Products

## Barbieri spectrophotometers



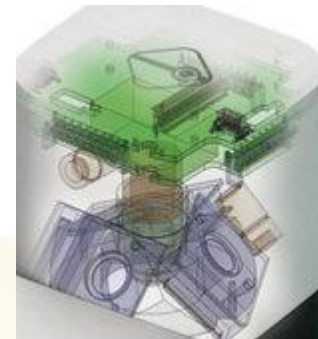
Spectro LFP qb for Large Format Printing



Spectro Pad as portable solution for roll-to-roll Format Printing



Spectro Swing for calibration in roll-to-roll-Format Printing



Customized measuring devices for OEM-manufacturers

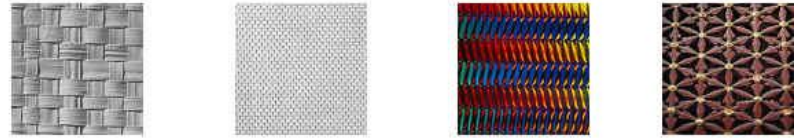
## 2. What is texture?

- “No formal definition of texture exists, intuitively this descriptor provides measures of properties such as smoothness, coarseness and regularity.” [Gonzalez, 2002]
- Usually refers to a scene taken from a single object/material characterized by spatial complexity

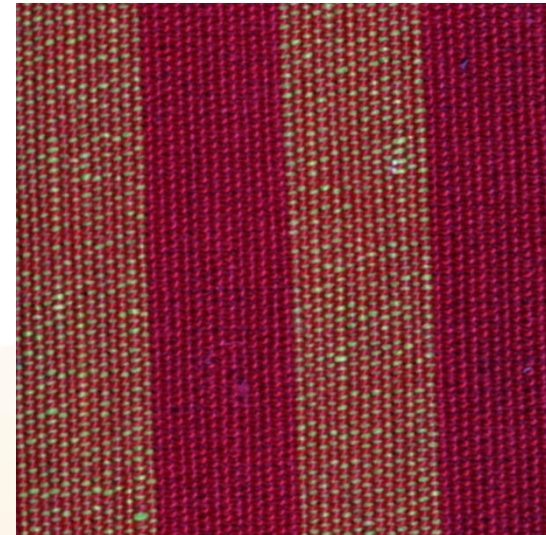
Directional



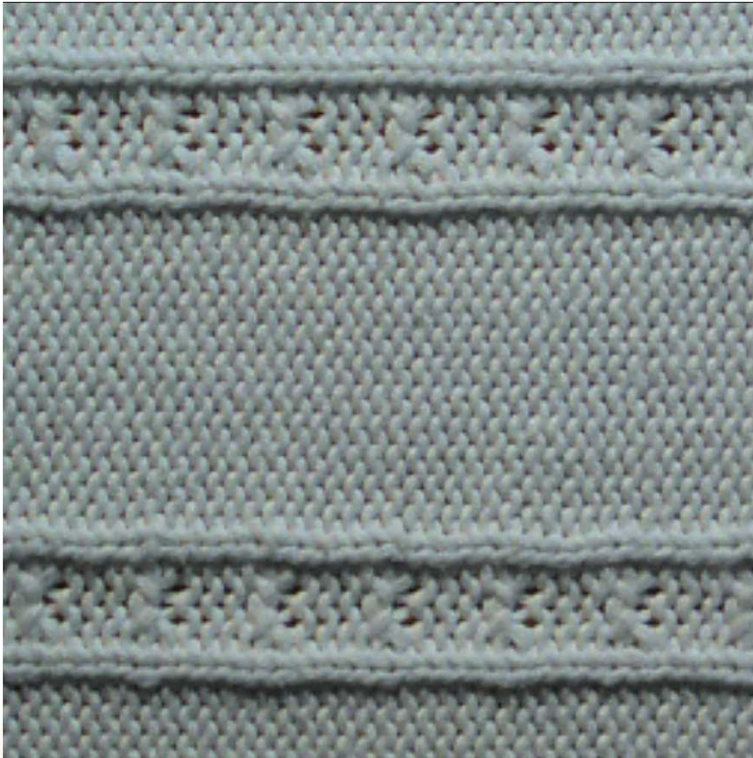
Periodic



Random



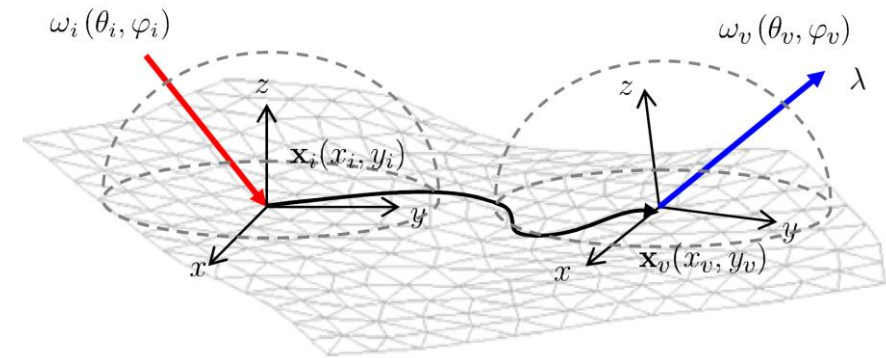
# Surface texture



From [Dong, 2005]

# 3. Texture models

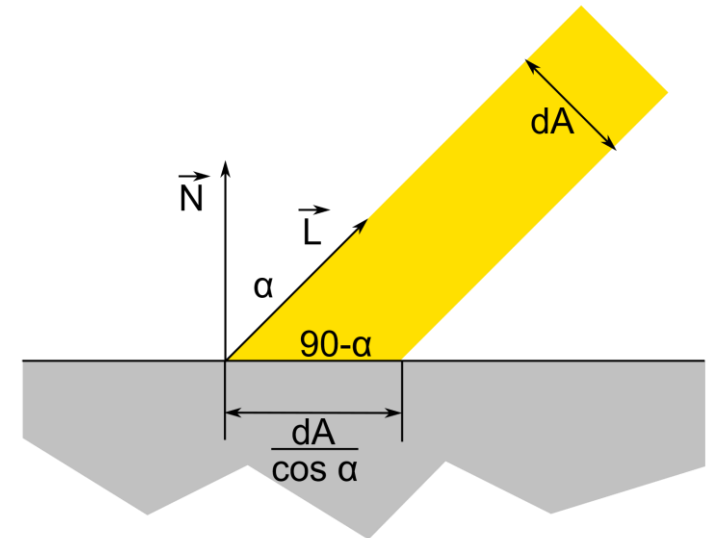
- General Reflectance Function (GRF): 16 variables source, detector, collision, emission coordinates + time and frequency of generation and detection
- Bidirectional Surface Scattering Reflectance Distribution Function (BSSRDF): 9D (scattering)
- Bidirectional Texture Function (BTF): 7D (surface)
- Bidirectional Reflectance Distribution Function (BRDF): 5D (point)
- Drawbacks: lengthy and expensive processes, cumbersome data management



From [Haindl, 2013]

# Lambertian reflectance model

- Property of ideal diffusely reflecting surface
- Surface reflectance is isotropic
- It is impossible to tell where the incident light comes from
- No specular peak
- Real world examples: matte paper, flat paint, opal glass

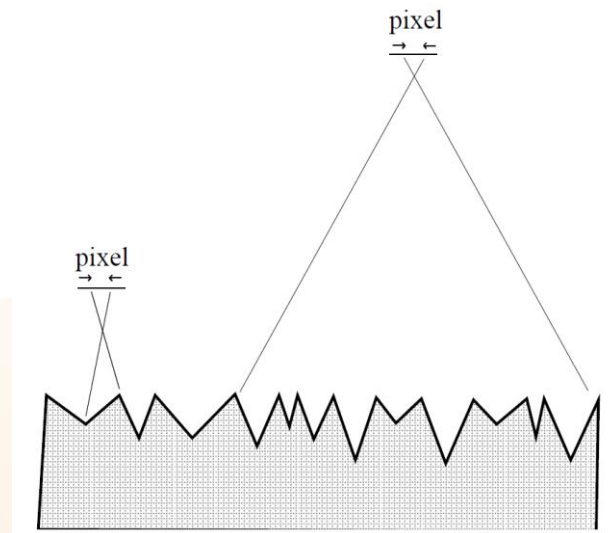
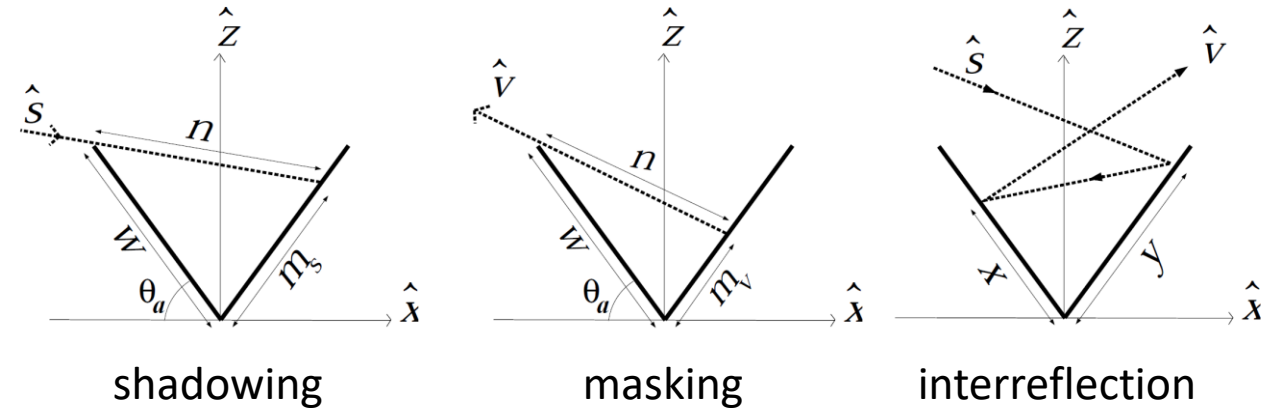


From [wikipedia]



# Oren-Nayar reflectance model

- Comprehensive model for body reflectance from surfaces with macroscopic roughness
- Accounts for complex geometric and radiometric phenomena (masking, shadowing, interreflections)
- Based on V-cavities
- Depends on the acquisition system (e.g. resolution of pixels)



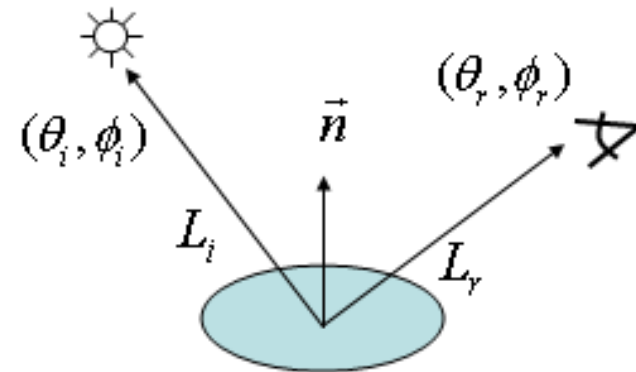
# Oren-Nayar reflectance model

$$L_r = \frac{\rho}{\pi} \cos \theta_i [A(\sigma) + B(\sigma) \max(0, \cos(\phi_i - \phi_r)) \sin(\max(\theta_i, \theta_r)) \tan(\min(\theta_i, \theta_r))] E_0$$

- Statistical model
- Effective for rough diffuse surfaces, such as, plaster, sand, clay, and cloth

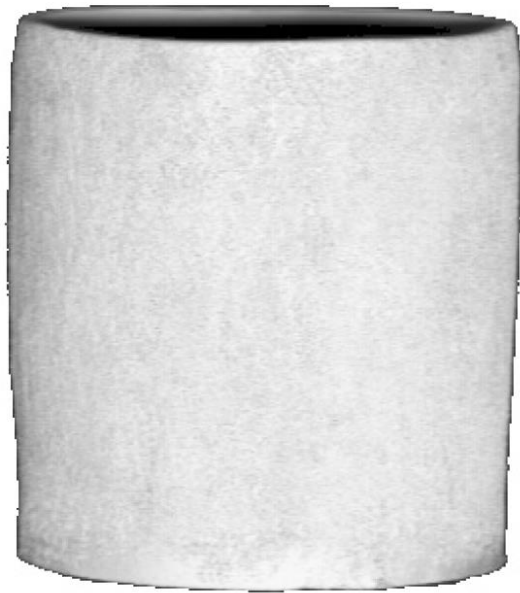
- $A(\sigma) = 1 - 0.5 \frac{\sigma^2}{\sigma^2 + 0.33}$

- $B(\sigma) = 0.45 \frac{\sigma^2}{\sigma^2 + 0.09}$

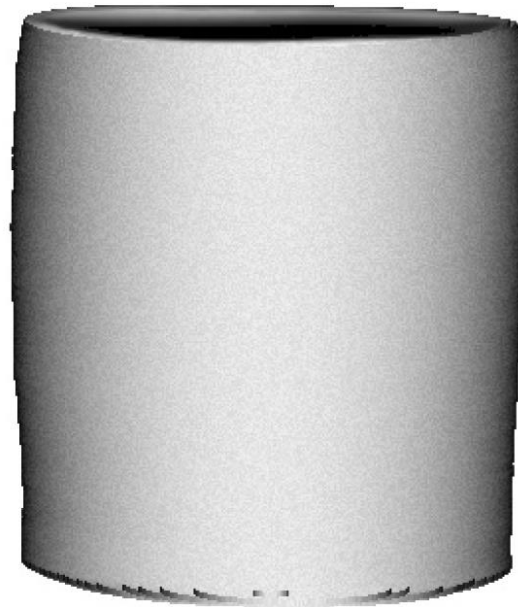


From [wikipedia]

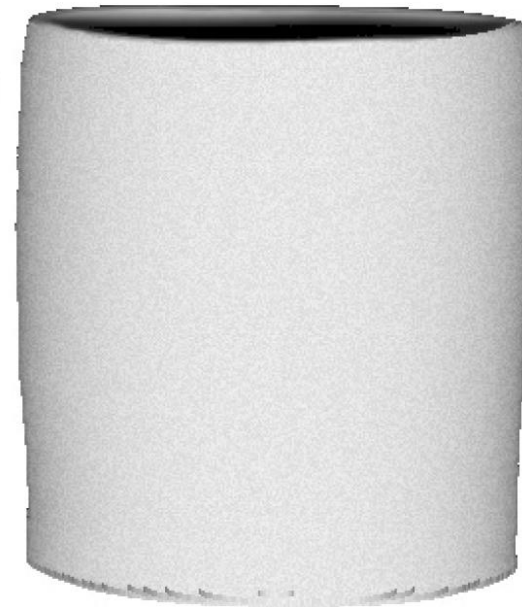
# Oren–Nayar reflectance model



(a) Image



(b) Lambertian

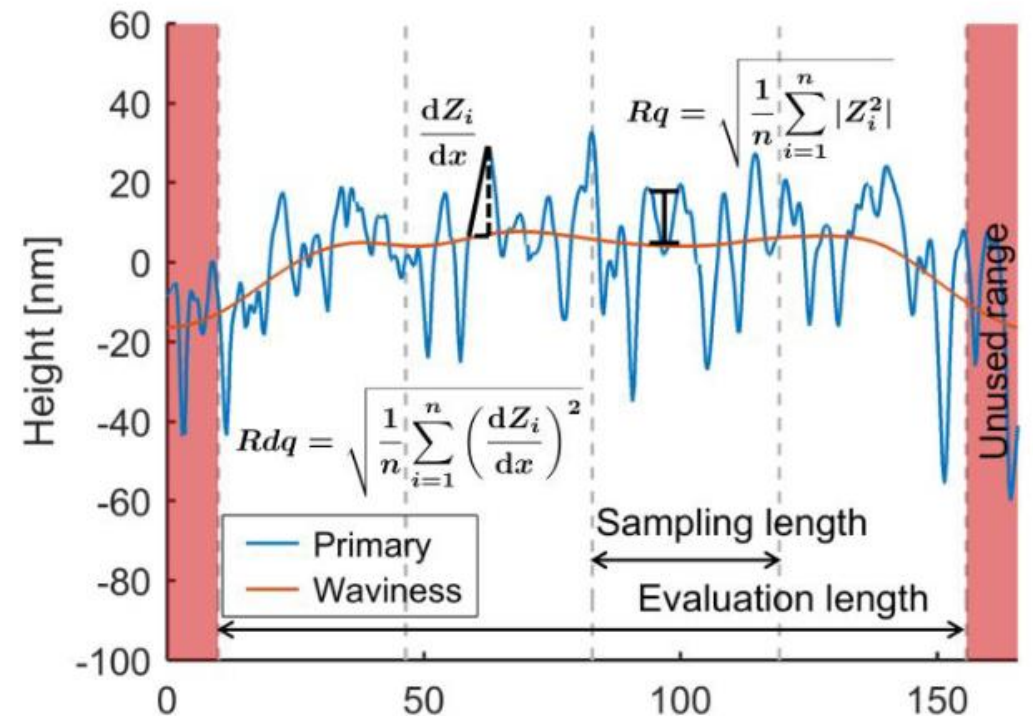


(c) Model

From [Oren, 1994]

# Roughness

- More models exist
- E.g., Principled BRDF
- $Rdq = \sqrt{\frac{1}{N} \sum_{i=1}^N \left(\frac{dZ}{dx}\right)_i^2}$
- Lambertian and Oren-Nayar models can be mixed

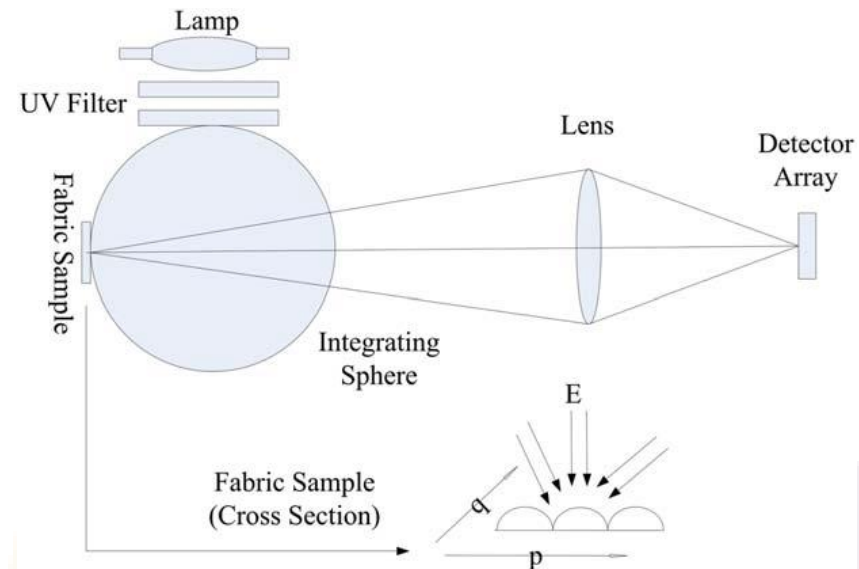
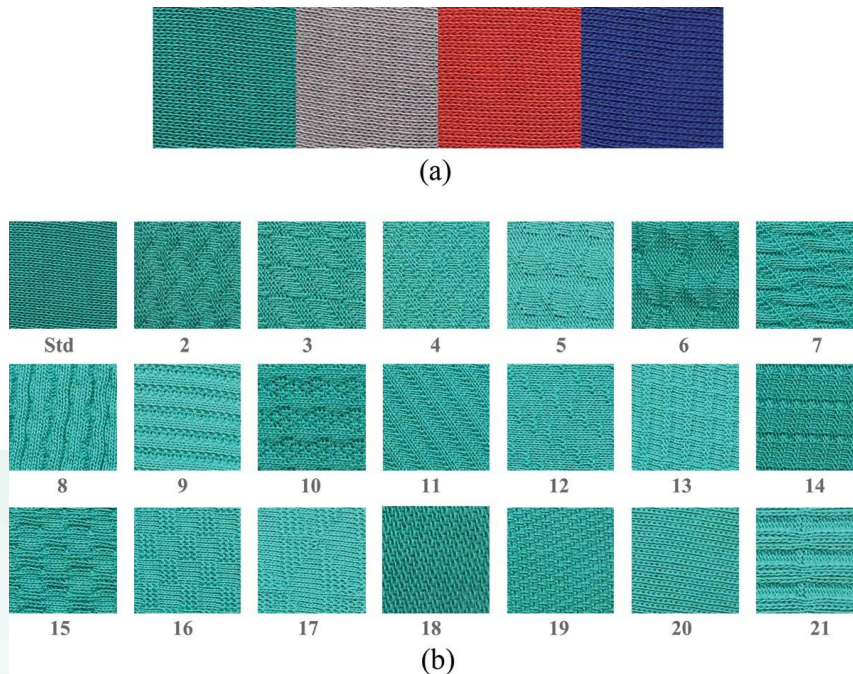


From [Feidenhans'l, 2015]

# Luo texture correction model

- Use reflectance model to correct colour measurements of textiles
- The correction must be done in CIEXYZ, given linearity with reflectance

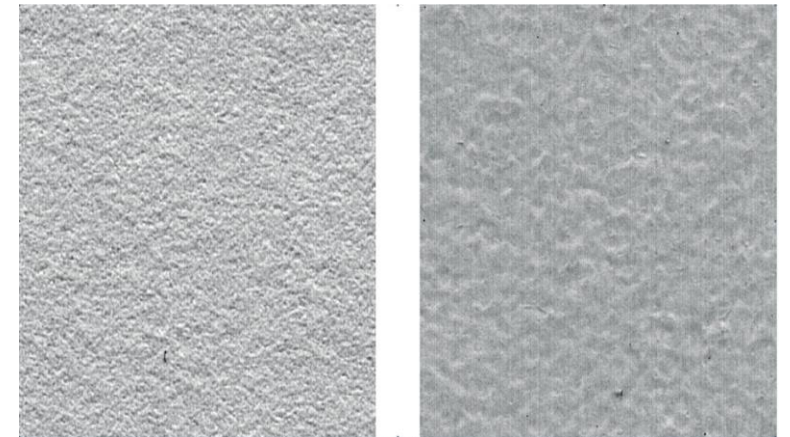
$$X = \frac{\iint_{p,q} m_b(p,q)H(p,q)dpdq}{A_r} \int_{\lambda} E(\lambda)R(\lambda)\bar{x}(\lambda)d\lambda = C \cdot X_{norm}$$



From [Luo, 2014]

# 4. Roughness correction in iccMAX

- Extension of ICC v4
- v5 in header
- Backwards compatibility
- ISO 20677
- Novelties examples:
- Extended connection space (e.g. flexible PCS, illuminant, CMFs)
- multiProcessingElements (matrices, LUTs, CAM and Calc elements)
- Spectral and BRDF support
- Height/normal map can be stored but not used in profile
- Can be used for rendering



From [Specification ICC.2:2019]

# The Calc element

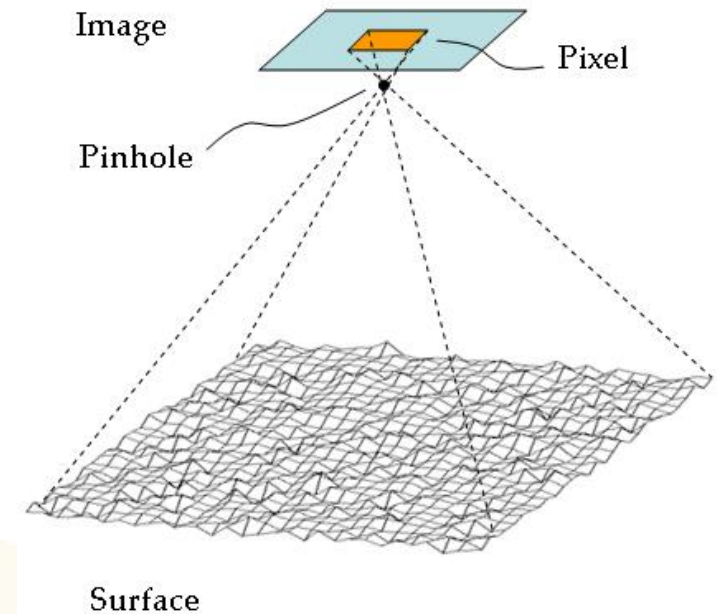
- MultiProcessElement
- Stack-based programming language
- Uses reverse polish notation:  $2 * 4 \rightarrow 2\ 4\ mul$
- Structure of CalculatorElement:

```
<CalculatorElement InputChannels="in" OutputChannels="out" InputNames="..." OutputNames="...">  
  <Imports> ... </Imports>  
  <Variables> ... </Variables>  
  <Macros> ... </Macros>  
  <SubElements>... </SubElements>  
  
  <MainFunction>Extended Textual Representation of Operations</MainFunction>  
</CalculatorElement>
```

- The data is private to the MultiProcessElement
- Stack empty at the start

# Implementation

- Two texture correction models: Lambertian and Oren–Nayar
- Purpose: correction of colour measurement on complex surface
- $XYZ_{norm} = XYZ_{meas} / C$
- $C_{Lambert} = \mu(\cos(\theta_i))$
- $C_{Oren-Nayar} = \mu(\cos \theta_i [A(\sigma) + B(\sigma) \max(0, \cos(\phi_i - \phi_r)) \sin(\max(\theta_i, \theta_r)) \tan(\min(\theta_i, \theta_r))])]$
- Single profile, CIEXYZ data colour space, CIEXYZ PCS
- Relative Colorimetric rendering intent
- ColorSpace ('spac') profile
- Correction implemented in multiProcessElement, A2B1 tag
- B2A1 tag implements  $XYZ_{meas} = C \cdot XYZ_{norm}$



From [wikipedia]

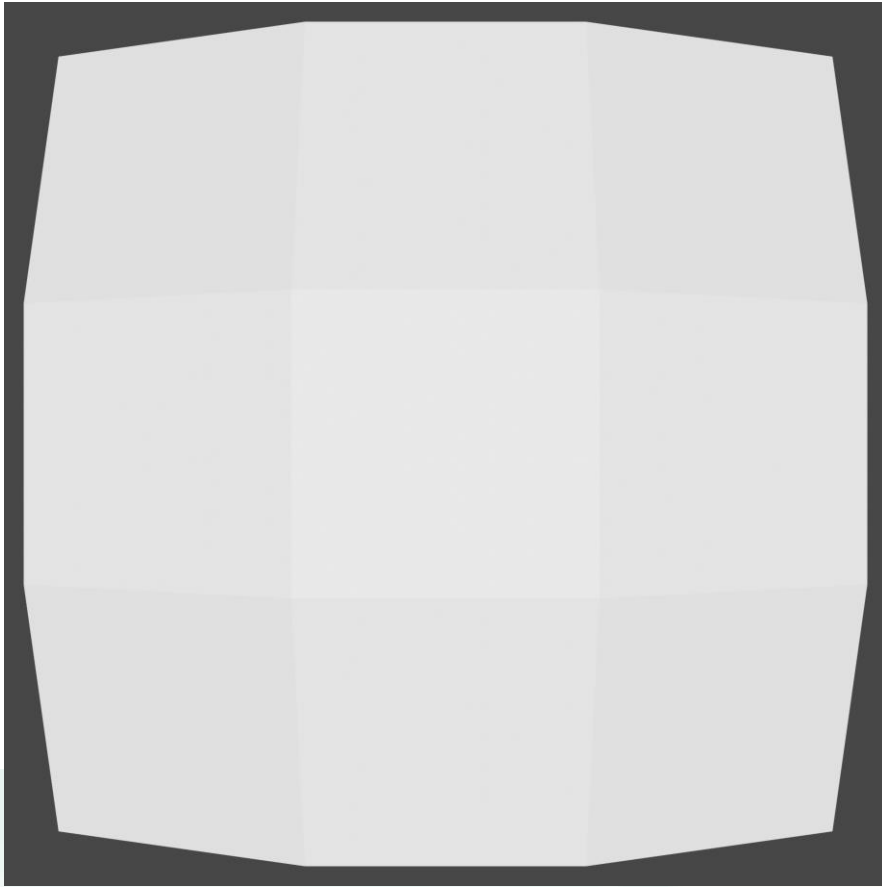


# Lambertian model correction

- $XYZ_{norm} = XYZ_{meas} / \mu(\cos(\theta_i))$
- Declarations:

```
25 <multiProcessElementType>
26   <TagSignature>A2B1</TagSignature>
27   <MultiProcessElements InputChannels="3" OutputChannels="3">
28     <CalculatorElement InputChannels="3" OutputChannels="3">
29       <Imports>
30         <Import Filename="import_lamb.xml"/>
31       </Imports>
32       <Variables>
33         <Declare Name="myVector" Size="9"/>
34       </Variables>
35       <Macros>
36         <!-- Macro to convert degrees to radians -->
37         <Macro Name="torad">3.14159265359 mul 180 div</Macro>
38       </Macros>
39     <MainFunction>
```

# 3D structure



Front



Side

# Lambertian model correction

- import\_lamb.xml:

```
1 <?xml version="1.0" encoding="UTF-8"?>
2 <IccCalcImport>
3   <Macros>
4     <!-- Map of polar angles of incident light with each facelet -->
5     <Macro Name="ti">
6       44.14 44.14 44.14
7       55.00 45.00 35.00
8       44.14 44.14 44.14
9     </Macro>
10  </Macros>
11 </IccCalcImport>
```

# Lambertian model correction

- Main function:

```
39 |           <MainFunction>
40 | {
41 | in(0,3)
42 | % Load normal map
43 | call{ti}
44 | % Calculate cosine and save in myVector
45 | call{torad} cos tput{myVector[0]}
46 | call{torad} cos tput{myVector[1]}
47 | call{torad} cos tput{myVector[2]}
48 | call{torad} cos tput{myVector[3]}
49 | call{torad} cos tput{myVector[4]}
50 | call{torad} cos tput{myVector[5]}
51 | call{torad} cos tput{myVector[6]}
52 | call{torad} cos tput{myVector[7]}
53 | call{torad} cos tput{myVector[8]}
54 | % Calculate average cosine
55 | tget{myVector} sum(9)
56 | 9 div
57 | % Use it to correct XYZ
58 | copy copy
59 | div(3)
60 | out(0,3)
61 | }
62 |           </MainFunction>
```

# Oren-Nayar model correction

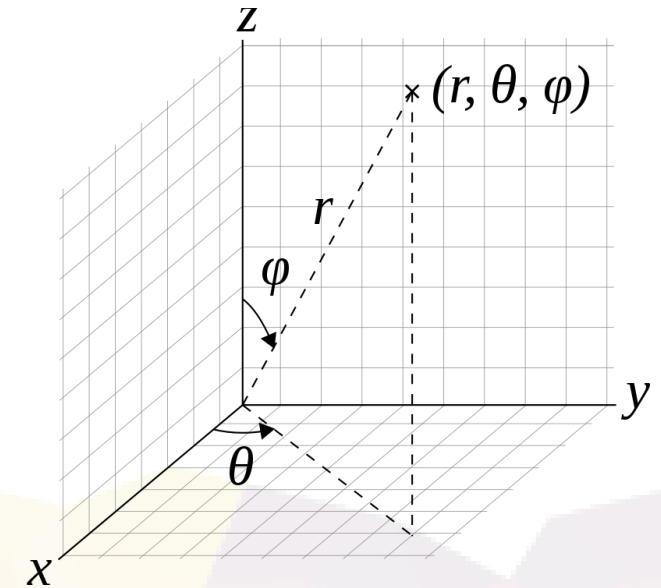
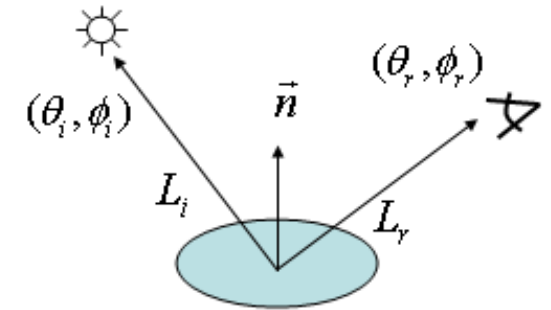
- $XYZ_{norm} = XYZ_{meas} / \mu (\cos \theta_i [A(\sigma) + B(\sigma) \max(0, \cos(\phi_i - \phi_r))] \sin(\max(\theta_i, \theta_r)) \tan(\min(\theta_i, \theta_r)))$
- Declarations:

```
25 <multiProcessElementType>
26   <TagSignature>A2B1</TagSignature>
27   <MultiProcessElements InputChannels="3" OutputChannels="3">
28     <CalculatorElement InputChannels="3" OutputChannels="3">
29       <Imports>
30         <Import Filename="import_oren.xml"/>
31       </Imports>
32       <Variables>
33         <Declare Name="cos_ti" Size="9"/>
34         <Declare Name="A"/>
35         <Declare Name="B"/>
36         <Declare Name="phi_i" Size="9"/>
37         <Declare Name="phi_r" Size="9"/>
38         <Declare Name="t_i" Size="9"/>
39         <Declare Name="t_r" Size="9"/>
40         <Declare Name="cos_diff" Size="9"/>
41         <Declare Name="sin_alpha" Size="9"/>
42         <Declare Name="tan_beta" Size="9"/>
43       </Variables>
```

# Oren-Nayar model correction

- import\_oren.xml:

```
1 <?xml version="1.0" encoding="UTF-8"?>
2 <IccCalcImport>
3   <Macros>
4     <!-- Here are stored the parameters of the Oren-Nayar correction model -->
5     <!-- Std dev of the model -->
6     <Macro Name="sigma">
7       0.50
8     </Macro>
9     <!-- Map of polar angles of incident light with each facelet -->
10    <Macro Name="ti">
11      44.14 44.14 44.14
12      55.00 45.00 35.00
13      44.14 44.14 44.14
14    </Macro>
15    <!-- Map of azimuth angles of incident light with each facelet -->
16    <Macro Name="phii">
17      -125.15 9.85 54.85
18      0.00 0.00 0.00
19      144.85 350.15 -35.15
20    </Macro>
21    <!-- Map of polar angles of detector with each facelet -->
22    <Macro Name="tr">
23      80.00 10.00 80.00
24      10.00 0.00 10.00
25      80.00 10.00 80.00
26    </Macro>
27    <!-- Map of azimuth angles of detector with each facelet -->
28    <Macro Name="phir">
29      -45.00 90.00 135.00
30      0.00 0.00 180.00
31      -135.00 270.00 45.00
32    </Macro>
33  </Macros>
34 </IccCalcImport>
```



From [wikipedia]

# Oren-Nayar model correction

- Conversion to radians and  $\cos(\theta_i)$ :

```
44 <Macro>
45 <!-- Macro to convert degrees to radians -->
46 <Macro Name="torad">3.14159265359 mul 180 div</Macro>
47 <Macro Name="calc_cos_ti">
48   % Load illumination cosines map
49   call{ti} tput{t_i}
50   % Calculate cosine and save in cos_ti
51   tget{t_i[0]} call{torad} cos tput{cos_ti[0]}
52   tget{t_i[1]} call{torad} cos tput{cos_ti[1]}
53   tget{t_i[2]} call{torad} cos tput{cos_ti[2]}
54   tget{t_i[3]} call{torad} cos tput{cos_ti[3]}
55   tget{t_i[4]} call{torad} cos tput{cos_ti[4]}
56   tget{t_i[5]} call{torad} cos tput{cos_ti[5]}
57   tget{t_i[6]} call{torad} cos tput{cos_ti[6]}
58   tget{t_i[7]} call{torad} cos tput{cos_ti[7]}
59   tget{t_i[8]} call{torad} cos tput{cos_ti[8]}
60 </Macro>
```

# Oren-Nayar model correction

- $A(\sigma)$  and  $B(\sigma)$ :

```
60 </Macro>
61 <Macro Name="calc_A">
62     call{sigma} call{sigma} mul
63     tsav(0,1)
64     tget(0,1) 0.33 add
65     div
66     -0.5 mul
67     1 add
68     tput{A}
69 </Macro>
70 <Macro Name="calc_B">
71     call{sigma} call{sigma} mul
72     tsav(0,1)
73     tget(0,1) 0.09 add
74     div
75     0.45 mul
76     tput{B}
77 </Macro>
```



# Oren-Nayar model correction

- $\max(0, \cos(\phi_i - \phi_r))$ :

```
78 <Macro Name="calc_cos_diff">
79     call{phii} tput{phi_i}
80     call{phir} tput{phi_r}
81     tget{phi_i[0]} tget{phi_r[0]} sub call{torad} cos 0 max tput{cos_diff[0]}
82     tget{phi_i[1]} tget{phi_r[1]} sub call{torad} cos 0 max tput{cos_diff[1]}
83     tget{phi_i[2]} tget{phi_r[2]} sub call{torad} cos 0 max tput{cos_diff[2]}
84     tget{phi_i[3]} tget{phi_r[3]} sub call{torad} cos 0 max tput{cos_diff[3]}
85     tget{phi_i[4]} tget{phi_r[4]} sub call{torad} cos 0 max tput{cos_diff[4]}
86     tget{phi_i[5]} tget{phi_r[5]} sub call{torad} cos 0 max tput{cos_diff[5]}
87     tget{phi_i[6]} tget{phi_r[6]} sub call{torad} cos 0 max tput{cos_diff[6]}
88     tget{phi_i[7]} tget{phi_r[7]} sub call{torad} cos 0 max tput{cos_diff[7]}
89     tget{phi_i[8]} tget{phi_r[8]} sub call{torad} cos 0 max tput{cos_diff[8]}
90 </Macro>
```

# Oren-Nayar model correction

- $\sin(\max(\theta_i, \theta_r))$ :

```
91 
92
93 <Macro Name="calc_sin_alpha">
94     call{tr} tput{t_r}
95     tget{t_i[0]} tget{t_r[0]} max call{torad} sin tput{sin_alpha[0]}
96     tget{t_i[1]} tget{t_r[1]} max call{torad} sin tput{sin_alpha[1]}
97     tget{t_i[2]} tget{t_r[2]} max call{torad} sin tput{sin_alpha[2]}
98     tget{t_i[3]} tget{t_r[3]} max call{torad} sin tput{sin_alpha[3]}
99     tget{t_i[4]} tget{t_r[4]} max call{torad} sin tput{sin_alpha[4]}
100    tget{t_i[5]} tget{t_r[5]} max call{torad} sin tput{sin_alpha[5]}
101    tget{t_i[6]} tget{t_r[6]} max call{torad} sin tput{sin_alpha[6]}
102    tget{t_i[7]} tget{t_r[7]} max call{torad} sin tput{sin_alpha[7]}
103    tget{t_i[8]} tget{t_r[8]} max call{torad} sin tput{sin_alpha[8]}
104 </Macro>
```

# Oren-Nayar model correction

- $\tan(\min(\theta_i, \theta_r))$ :

```
103  <Macro Name="calc_tan_beta">  
104     tget{t_i[0]} tget{t_r[0]} min call{torad} tan tput{tan_beta[0]}  
105     tget{t_i[1]} tget{t_r[1]} min call{torad} tan tput{tan_beta[1]}  
106     tget{t_i[2]} tget{t_r[2]} min call{torad} tan tput{tan_beta[2]}  
107     tget{t_i[3]} tget{t_r[3]} min call{torad} tan tput{tan_beta[3]}  
108     tget{t_i[4]} tget{t_r[4]} min call{torad} tan tput{tan_beta[4]}  
109     tget{t_i[5]} tget{t_r[5]} min call{torad} tan tput{tan_beta[5]}  
110     tget{t_i[6]} tget{t_r[6]} min call{torad} tan tput{tan_beta[6]}  
111     tget{t_i[7]} tget{t_r[7]} min call{torad} tan tput{tan_beta[7]}  
112     tget{t_i[8]} tget{t_r[8]} min call{torad} tan tput{tan_beta[8]}  
113 </Macro>
```

# Oren-Nayar model correction

- Main function:

```
116 | | | <MainFunction>
117 | {
118 | in(0,3)
119 | % Calculate cosine of illumination and save in cos_ti
120 | call{calc_cos_ti}
121 | % Calculate coefficient A
122 | call{calc_A}
123 | % Calculate coefficient B
124 | call{calc_B}
125 | % Calculate cosine of difference
126 | call{calc_cos_diff}
127 | % Calculate sin(alpha)
128 | call{calc_sin_alpha}
129 | % Calculate tan(beta)
130 | call{calc_tan_beta}
131 | % Put everything together to get the correction coefficient
132 | tget{B} tget{cos_diff[0]} mul tget{sin_alpha[0]} mul tget{tan_beta[0]} mul tget{A} sum tget{cos_ti[0]} mul
133 | tget{B} tget{cos_diff[1]} mul tget{sin_alpha[1]} mul tget{tan_beta[1]} mul tget{A} sum tget{cos_ti[1]} mul
134 | tget{B} tget{cos_diff[2]} mul tget{sin_alpha[2]} mul tget{tan_beta[2]} mul tget{A} sum tget{cos_ti[2]} mul
135 | tget{B} tget{cos_diff[3]} mul tget{sin_alpha[3]} mul tget{tan_beta[3]} mul tget{A} sum tget{cos_ti[3]} mul
136 | tget{B} tget{cos_diff[4]} mul tget{sin_alpha[4]} mul tget{tan_beta[4]} mul tget{A} sum tget{cos_ti[4]} mul
137 | tget{B} tget{cos_diff[5]} mul tget{sin_alpha[5]} mul tget{tan_beta[5]} mul tget{A} sum tget{cos_ti[5]} mul
138 | tget{B} tget{cos_diff[6]} mul tget{sin_alpha[6]} mul tget{tan_beta[6]} mul tget{A} sum tget{cos_ti[6]} mul
139 | tget{B} tget{cos_diff[7]} mul tget{sin_alpha[7]} mul tget{tan_beta[7]} mul tget{A} sum tget{cos_ti[7]} mul
140 | tget{B} tget{cos_diff[8]} mul tget{sin_alpha[8]} mul tget{tan_beta[8]} mul tget{A} sum tget{cos_ti[8]} mul
141 | % Calculate average correction factor
142 | sum(9) 9 div
143 | % Use it to correct XYZ
144 | copy copy
145 | div(3)
146 | out(0,3)
147 | }
148 | | | </MainFunction>
```

# Input

- The .xml file can be converted in .icc profile with iccFromXml.exe
- Applied to image with iccApplyProfiles.exe, to named input with iccApplyNamedCMM.exe
- We used:

```
iccApplyNamedCMM.exe input_oren.txt 3 0 oren_nayar_correction.icc 3
```

- Final encoding: icEncodeFloat
- Interpolation: Linear
- Rendering intent: Absolute
- Input file:

```
1 'XYZ' ; Data Format
2 icEncodeFloat ; Encoding
3
4 0.5 0.5 0.5
```

# Results

- Output:

```
'XYZ ' ; Data Format  
icEncodeFloat ; Encoding  
  
;Source Data Format: 'dXYZ'  
;Source Data Encoding: icEncodeFloat  
;Source data is after semicolon  
  
;Profiles applied  
; oren_nayar_correction.icc  
  
0.8689 0.8689 0.8689 ; 0.5000 0.5000 0.5000
```

**Thank you for your attention**

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[www.barbierielectronic.com](http://www.barbierielectronic.com)

**QUESTIONS?**



# References

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